### **CMOS** Oscillators

### INTRODUCTION

This note describes several square wave oscillators that can be built using CMOS logic elements. These circuits offer the following advantages:

- Guaranteed startability
- Relatively good stability with respect to power supply variations
- Operation over a wide supply voltage range (3V to 15V)
- Operation over a wide frequency range from less than 1 Hz to about 15 MHz
- Low power consumption (see AN-90)
- Easy interface to other logic families and elements including TTL

Several RC oscillators and two crystal controlled oscillators are described. The stability of the RC oscillator will be sufficient for the bulk of applications; however, some applications will probably require the stability of a crystal. Some applications that require a lot of stability are:

- Timekeeping over a long interval. A good deal of stability is required to duplicate the performance of an ordinary wrist watch (about 12 ppm). This is, of course, obtainable with a crystal. However, if the time interval is short and/or the resolution of the timekeeping device is relatively large, an RC oscillator may be adequate. For example: if a stopwatch is built with a resolution of tenths of seconds and the longest interval of interest is two minutes, then an accuracy of 1 part in 1200 (2 minutes x 60 seconds/minute x 10 tenth/second) may be acceptable since any error is less than the resolution of the device.
- 2. When logic elements are operated near their specified limits. It may be necessary to maintain clock frequency accuracy within very tight limits in order to avoid exceeding the limits of the logic family being used, or in which the timing relationships of clock signals in dynamic MOS memory or shift register systems must be preserved.
- 3. Baud rate generators for communications equipment.
- Any system that must interface with other tightly specified systems. Particularly those that use a "handshake" technique in which Request or Acknowledge pulses must be of specific widths.

### LOGICAL OSCILLATORS

Before describing any specific circuits, a few words about logical oscillators may clear up some recurring confusion.

Any odd number of inverting logic gates will oscillate if they are tied together in a ring as shown in *Figure 1*. Many beginning logic designers have discovered this (to their chagrin) by inadvertently providing such a path in their designs. However, some people are confused by the circuit in *Figure 1* because they are accustomed to seeing sinewave oscillators implemented with positive feedback, or amplifiers with non-inverting gain. Since the concept of phase shift becomes a little strained when the inverters remain in their linear region for such a short period, it is far more straightforward to analyze the circuit from the standpoint of ideal



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switches with finite propagation delays rather than as amplifiers with 180° phase shift. It then becomes obvious that a "1" chases itself around the ring and the network oscillates.



ADDITIONAL GATES

FIGURE 1. Odd Number of Inverters Will Always Oscillate

The frequency of oscillation will be determined by the total propagation delay through the ring and is given by the follow-ing equation.

$$f = \frac{1}{2nTp}$$

Where:

f = frequency of oscillation

Tp = Propagation delay per gate

n = number of gates

This is not a practical oscillator, of course, but it does illustrate the maximum frequency at which such an oscillator will run. All that must be done to make this a useful oscillator is to slow it down to the desired frequency. Methods of doing this are described later.

To determine the frequency of oscillation, it is necessary to examine the propagation delay of the inverters. CMOS propagation delay depends on supply voltage and load capacitance. Several curves for propagation delay for Fairchild's 74C line of CMOS gates are reproduced in *Figure 3*. From these, the natural frequency of oscillation of an odd number of gates can be determined.

An example may be instructive.

Assume the supply voltage is 10V. Since only one input is driven by each inverter, the load capacitance on each inverter is at most about 8 pF. Examine the curve in *Figure 3c* that is drawn for V<sub>CC</sub> = 10V and extrapolate it down to 8 pF. We see that the curve predicts a propagation delay of about 17 ns. We can then calculate the frequency of oscillation for three inverters using the expression mentioned above. Thus:

$$f = \frac{1}{2 \times 3 \times 17 \times 10^{-9}} = 9.8 \text{ MHz}$$

Lab work indicates this is low and that something closer to 16 MHz can be expected. This reflects the conservative nature of the curves in *Figure 3*.

Since this frequency is directly controlled by propagation delays, it will vary a great deal with temperature, supply voltage, and any external loading, as indicated by the graphs in *Figure 3.* In order to build a usefully stable oscillator it is nec-



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Note that the voltage  $V_2$  will be clamped by input diodes when  $V_1$  is greater than  $V_{CC}$  or more negative than ground. During this portion of the cycle current will flow through R2. At all other times the only current through R2 is a very minimal leakage term. Note also that as soon as  $V_1$  passes through threshold (about 50% of supply) and the input to the last inverter begins to change,  $V_1$  will also change in a direction that reinforces the switching action; i.e., providing positive feedback. This further enhances the stability and predictability of the network.

This oscillator is fairly insensitive to power supply variations due largely to the threshold tracking close to 50% of the supply voltage. Just how stable it is will be determined by the frequency of oscillation; the lower the frequency the more stability and vice versa. This is because propagation delay and the effect of threshold shifts comprise a smaller portion of the overall period. Stability will also be enhanced if R1 is made large enough to swamp any variations in the CMOS output resistance.

## TWO GATE OSCILLATOR WILL NOT NECESSARILY OSCILLATE

A popular oscillator is shown in *Figure 5a*. The only undesirable feature of this oscillator is that it may not oscillate. This is readily demonstrated by letting the value of C go to zero. The network then degenerates into *Figure 5b*, which obviously will not oscillate. This illustrates that there is some value of C1 that will not force the network to oscillate. The real difference between this two gate oscillator and the three gate oscillator while the three gate network will always oscillate willingly and is simply slowed down by the capacitor. The three gate network will always oscillate of C1 but the two gate oscillator will not oscillate will not oscillate. The three gate network will always oscillate willingly and is simply slowed down by the capacitor. The three gate network will always oscillate will not oscillate will not oscillate will not oscillate.



The only advantage the two gate oscillator has over the three gate oscillator is that it uses one less inverter. This may or may not be a real concern, depending on the gate count in each user's specific application. However, the next section offers a real minimum parts count oscillator.

# A SINGLE SCHMITT TRIGGER MAKES AN OSCILLATOR

*Figure 6* illustrates an oscillator made from a single Schmitt trigger. Since the MM74C14 is a hex Schmitt trigger, this oscillator consumes only one sixth of a package. The remaining 5 gates can be used either as ordinary inverters like the MM74C04 or their Schmitt trigger characteristics can be used to advantage in the normal manner. Assuming these five inverters can be used elsewhere in the system, *Figure 6* must represent the ultimate in low gate count oscillators.





Voltage V<sub>1</sub> is depicted in *Figure 7* and changes between the two thresholds of the Schmitt trigger. If these thresholds were constant percentages of V<sub>CC</sub> over the supply voltage range, the oscillator would be insensitive to variations in V<sub>CC</sub>. However, this is not the case. The thresholds of the Schmitt trigger vary enough to make the oscillator exhibit a good deal of sensitivity to V<sub>CC</sub>.



Applications that do not require extreme stability or that have access to well regulated supplies should not be bothered by

FIGURE 7. Waveforms for Schmitt Trigger Oscillator in Figure 6

### A CMOS CRYSTAL OSCILLATOR

*Figure 8* illustrates a crystal oscillator that uses only one CMOS inverter as the active element. Any odd number of inverters may be used, but the total propagation delay through the ring limits the highest frequency that can be obtained. Obviously, the fewer inverters that are used, the higher the maximum possible frequency.

#### CONCLUSIONS

A large number of oscillator applications can be implemented with the extremely simple, reliable, inexpensive and versatile CMOS oscillators described in this note. These oscillators consume very little power compared to most other approaches. Each of the oscillators requires less than one full package of CMOS inverters of the MM74C04 variety. Frequently such an oscillator can be built using leftover gates of the MM74C00, MM74C02, MM74C10 variety. Stability superior to that easily attainable with TTL oscillators is readily attained, particularly at lower frequencies. These oscillators are so versatile, easy to build, and inexpensive that they should find their way into many diverse designs.



FIGURE 8. Crystal Oscillator

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