# A Study of the Crystal Oscillator for CMOS-COPS™

National Semiconductor Application Note 400 Abdul Aleaf August 1986



Study of the Crystal Oscillator for CMOS-COPS

# INTRODUCTION

The most important characteristic of CMOS-COPS is its low power consumption. This low power feature does not exist in TTL and NMOS systems which require the selection of low power IC's and external components to reduce power consumption.

The optimization of external components helps decrease the power consumption of CMOS-COPS based systems even more.

A major contributor to power consumption is the crystal oscillator circuitry.

Table I presents experimentally observed data which compares the current drain of a crystal oscillator vs. an external squarewave clock source.

The main purpose of this application note is to provide experimentally observed phenomena and discuss the selection of suitable oscillator circuits that cover the frequency range of the CMOS-COPS.

Table I clearly shows that an unoptimized crystal oscillator draws more current than an external squarewave clock. An RC oscillator draws even more current because of the slow rising signal at the CKI input.

Although there are few components involved in the design of the oscillator, several effects must be considered. If the requirement is only for a circuit at a standard frequency which starts up reliably regardless of precise frequency stability, power dissipation and etc., then the user could directly consult the data book and select a suitable circuit with proper components. If power consumption is a major requirement, then reading this application note might be helpful.

# WHICH IS THE BEST OSCILLATOR CIRCUIT?

The Pierce Oscillator has many desirable characteristics. It provides a large output signal and drives the crystal at a low power level. The low power level leads to low power dissipation, especially at higher frequencies. The circuit has good short-term stability, good waveforms at the crystal, a frequency which is independent of power supply and temperature changes, low cost and usable at any frequency. As compared with other oscillator circuits, this circuit is not disturbed very much by connecting a scope probe at any point in the circuit, because it is a stable circuit and has low impedance. This makes it easier to monitor the circuit without any major disturbance. The Pierce oscillator has one disadvantage. The amplifier used in the circuit must have high gain to compensate for high gain losses in the circuitry surrounding the crystal.

#### TABLE I

A. Crystal oscillator vs. external squarewave COP410C change in current consumption as a function of frequency and voltage, chip held in reset, CKI is  $\div$  4.

I = total power supply current drain (at V<sub>CC</sub>).

Crystal

v <sub>cc</sub>	f <sub>ckl</sub>	Inst. cyc. time	ΙμΑ
2.4V	32 kHz	125 μs	8.5
5.0V	32 kHz	125 μs	83
2.4V	1 MHz	4 μs	199
5.0V	1 MHz	4 μs	360

#### External Squarewave

Vcc	f <sub>ckl</sub>	Inst. cyc. time	I
2.4V	32 kHz	125 μs	4.4 μΑ
5.0V	32 kHz	125 μs	10 μA
2.4V	1 MHz	4 μs	127 μA
5.0V	1 MHz	4 μs	283 μA

# WHAT IS A PIERCE OSCILLATOR?

The Pierce is a series resonant circuit, and its basic configuration is shown below.



For oscillation to occur, the Barkhausen criteria must be met: (1) The loop gain must be greater than one. (2) The phase shift around the loop must be 360°.

AN-40

COPS™ is a trademark of National Semiconductor Corp.

© 1995 National Semiconductor Corporation TL/DD/8439

RRD-B30M105/Printed in U. S. A.

Ideally, the inverting amplifier provides 180°, the  $R_1C_1$  integration network provides a 90° phase lag, and the crystal's impedance which is a pure resistance at series resonance together with  $C_2$  acts as a second integration network which provides another 90° phase lag. The time constants of the two RC phase shifting networks should be made as big as possible. This makes their phase shifts independent of any changes in resistance or capacitance values. However, big RC values introduce large gain losses and the selected amplifier should provide sufficient gain to satisfy gain requirement. CMOS inverters or discrete transistors can be used as amplifiers. An experimental evaluation of crystal oscillators using either type of amplifier is given within this report.

#### CRYSTAL OSCILLATORS USING CMOS-IC

The use of CMOS-IC's in crystal oscillators is quite popular. However, they are not perfect and could cause problems. The input characteristics of such IC's are good, but they are limited in their output drive capability.

The other disadvantage is the longer time delay in a CMOSinverter as compared to a discrete transistor. The longer this time delay the more power will be dissipated. This time delay is also different among different manufacturers.

As a characteristic of most CMOS-IC's the frequency sensitivity to power supply voltage changes is high. As a group, IC's do not perform very well when compared with discrete transistor circuits.

But let us not be discouraged. Low component count which leads to low cost is one good feature of IC oscillators.

As a rule, IC's work best at the low end of their frequency range and poorest at the high end.

Several types of crystal oscillators using CMOS-IC's have been found to work satisfactorily in some applications.

## CMOS-TWO INVERTER OSCILLATOR

The two inverter circuit shown in *Figure 2* is a popular one. The circuit is series resonant and uses two cascaded inverters for an amplifier.



Each inverter has a DC biasing resistor which biases the inverter halfway between the logic "1" and "0" states. This will help the inverters to amplify when the power is applied and the crystal will start oscillation.

The 74C family works better as compared with other CMOS-IC's. Will oscillate at a higher frequency and is less sensitive to temperature changes. The CMOS-COPS data sheet states that a crystal oscillator will typically draw 100  $\mu$ A more than an external clock source. However, the crystal oscillator described above will draw approximately as much current as an external squarewave clock. The experimental data presented below shows the comparison:

Chip held in Reset,  $V_{CC} = +5.0V$ f = 455 kHz, COP444C, CKI is  $\div 8$ 

Instruction cycle time =  $17.5 \,\mu s$ 

 $\mathsf{I} = \mathsf{total} \mathsf{ power supply} \left(\mathsf{V}_{CC}\right) \mathsf{ current} \mathsf{ drain}$ 

Oscillator Type	l (current drain)
Crystal Osc. (data sheet)	950 μA
Crystal Osc. (two inverter)	810 μA
Ext. Clock	790 μA

#### PIERCE IC OSCILLATOR

*Figure 3* shows a Pierce oscillator using CMOS inverter as an amplifier.



The gain of CMOS inverter is low, so the resistor  $R_1$  should be made small. This reduces gain losses. The output resistance of the inverter (Ro) can be the integrating resistor for the RoC<sub>I</sub> phase lag network.

Omitting  $R_1$  or with a small value of  $R_1$ , the crystal will be driven at a much higher voltage level. This will increase power dissipation.

For lower frequencies (i.e., 32 kHz), R<sub>1</sub> must be large enough so that the inverter won't overdrive the crystal. Also, if R<sub>1</sub> is too large we won't get an adequate signal back at the inverter's input to maintain oscillation. With large values of R<sub>1</sub> the inverter will remain in its linear region longer and will cause more power dissipation. Typically for 32 kHz, R<sub>1</sub> should be constrained by the relation.

$$\frac{1}{2\pi R_1 C_1} \ll 32 \text{ kHz}$$

At higher frequencies, selection of R<sub>1</sub> is again critical. In order to drive a heavy load at high frequency, the amplifier output impedance must be low. In order to isolate the oscillator output from C<sub>1</sub> so it can drive the following logic stages, then R<sub>1</sub> should be large. But again, R<sub>1</sub> must not be too large, otherwise it will reduce the loop gain.

The value of  $R_1$  is chosen to be roughly equal to the capacitive reactance of C1 at the frequency of operation, or the value of load impedance ZL.

Where 
$$Z_L = \frac{X_{c1}^2}{R_L}$$

 $R_L = R_S =$  series resistance of crystal

The small values of  $C_1$  and  $C_2$  will help minimize the gain reduction they introduce.

typically:  $C_1 = C_2 = 220 \text{ pF}$  at 1 MHz  $C_1=C_2=330\ \text{pF}$  at 2 MHz

### DISCRETE TRANSISTOR OSCILLATOR

As mentioned earlier, a discrete transistor circuit performs better than an IC circuit. The reason for this is that in a discrete transistor circuit it is easier to control the crystal's source and load resistances, the gain and signal amplitude. A discrete transistor circuit has shorter time delay, because it uses one or two transistors. This time delay should always be minimized, since it causes more power dissipation and shifts frequency with temperature changes. Figure 4 shows a basic Pierce oscillator using a transistor as an amplifier.



## FIGURE 4

The basic phase shift network consists of  $\rm C_{A_1},\,C_{B_2}$  and the crystal which looks inductive and is series resonant with  $C_{A_1}$  and  $C_{B_1}.$  The phase shift through the transistor is 180° and the total phase shift around the loop is 360°. The condition of a unity loop gain must also be satisfied.

$$\frac{V_A}{V_B} = -\left(\frac{C_B}{C_A}\right)$$
$$\frac{V_A}{V_B} = -\left(\frac{X_{CA}}{X_{CB}}\right)$$

For oscillation to occur, the transistor gain must satisfy the relation

$$G\left(\frac{V_A}{V_B}\right) \ge$$
, 1

where  $G = -g_{fe}Z_L$ 

 $g_{\mbox{fe}}$  is the transconductance of the transistor  $\rm Z_L$  is the load seen by the collector

$$Z_{\rm L} = \frac{X_{\rm B}^2}{1}$$
  $X_{\rm B} = -\frac{1}{1}$ 

$$Z_{L} = \frac{H_{B}}{Re}, \quad X_{B} = -\frac{H_{B}}{WC_{B}}$$

Re is the crystal's effective series resistance. The crystal's drive level

$$P_d = \frac{V_B 2_{Re}}{X_B 2}$$

This drive level should not exceed the manufacturer's spec. Certain biasing conditions might cause collector saturation. Collector saturation increases oscillator's dependence on the supply voltage and should be avoided.

The circuit of Figure 5 has been tested and has a very good performance.



This circuit will oscillate over a wide range of frequencies 2-20 MHz.

Voltage (V<sub>1</sub>) = 
$$\frac{(5)(1.5)}{1.5 + 4.7} = 1.21V$$
  
Base Current =  $\frac{1.21 \cdot V_{BE}}{39k} = 15.6 \ \mu A$ 

At Saturation (
$$V_{CE} = 0$$
)

$$I_{C (SAT)} = \frac{5}{1.2} = 4.2 \text{ mA}$$



Having 15.6  $\mu A$  of base current, for saturation to occur

$$E = \frac{4.2 \text{ mA}}{15.6 \mu \text{A}} = 269$$

hF

The DC beta for 3904 at 1 mA is 70 to 210, so no problem with saturation, even at lower supply voltages.

The current consumption (power supply V<sub>CC</sub> current drain) of COP444C using the above oscillation circuit is around 267  $\mu$ A.

The circuit of *Figure 6* is another configuration of discrete transistor oscillator.

The performance of above circuit is also good. The only drawback is that it does not provide larger output signal.

# CONCLUSION

As discussed within this report, a discrete transistor circuit gives better performance than an IC circuit. However, oscillators using discrete transistors are more expensive than those using IC's when assembly labor costs are included. So, the selection of either circuit is a trade-off between better performance and cost.

The data and circuits presented here are intended to be used only as a guide for the designer. The networks described are generally simple and inexpensive and have all been observed to be functional. They only provide greater flexibility in the oscillator selection for CMOS-COPS systems.

#### LIFE SUPPORT POLICY

NATIONAL'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF THE PRESIDENT OF NATIONAL SEMICONDUCTOR CORPORATION. As used herein:

 Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.  A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



National does not assume any responsibility for use of any circuitry described, no circuit patent licenses are implied and National reserves the right at any time without notice to change said circuitry and specifications.